604. ELECTRICAL & ELECTRONICS ENGINEERING (EE)

ENGINEERING MATHEMATICS

Matrices: Row and Column matrices, Square matrix, Diagonal matrix, Unit matrix, Null matrix, Symmetric and Skew symmetric matrices, Singular and Non singular matrices, Multiplication of matrices, Transpose and inverse of a matrix, Rank of a matrix, Eigen values and Eigen vectors, Cayley - Hamilton theorem. Matrix method of solution of simultaneous equations

Differential equations: First order equation (linear and nonlinear), Higher order linear differential equations with constant coefficients, Method of variation of parameters, Cauchy's and Euler's equations, Initial and boundary value problems, Partial Differential Equations and variable separable method.

Numerical Methods: Modified Euler's Method, Predictor Corrector method and R.K.Method of solving differential equations. Simpson's and Trapezoidal rule for integration.

Optimization Methods: Simplex method and Dynamic programming.

ELECTRICAL ENGINEERING

Electric Circuits: Network graph, KCL, KVL, node and mesh analysis, transient response of dc and ac networks; sinusoidal steady-state analysis, resonance, basic filter concepts; ideal current and voltage sources, Thevenin's, Norton's and Superposition and Maximum Power Transfer theorems, two-port networks, three phase circuits.

Signals and Systems: Representation of continuous and discrete-time signals: shifting and scaling operations; linear, time-invariant and causal systems; Fourier series representation of continuous periodic signals; sampling theorem; Fourier, Laplace and Z transforms.

Electrical Machines: Single phase transformer - equivalent circuit, phasor diagram, tests, regulation and efficiency; three phase transformers - connections, parallel operation; autotransformer; energy conversion principles; DC machines - types, windings, generator characteristics, armature reaction and commutation, starting and speed control of motors; three phase induction motors - principles, types, performance characteristics, starting and speed control; single phase induction motors; synchronous machines - performance, regulation and parallel operation of generators, motor starting, characteristics and applications; servo and stepper motors.

Power Systems: Basic power generation concepts; transmission line models and performance; cable performance, insulation; corona and radio interference; distribution systems; per-unit quantities; bus impedance and admittance matrices; load flow; voltage control; power factor correction; economic operation; symmetrical components; fault analysis; principles of over current, differential and distance protection; solid state relays and digital protection; circuit

breakers; system stability concepts, swing curves and equal area criterion; HVDC transmission and FACTS concepts.

Control Systems: Principles of feedback; transfer function; block diagrams; steady-state errors; Routh and Niquist techniques; Bode plots, root loci; lag, lead and lead-lag compensation; state space model; state transition matrix, controllability and observability.

Power Electronics and Drives: Semiconductor power diodes, transistors, thyristors, triacs, GTOs, MOSFETs and IGBTs - static characteristics and principles of operation; triggering circuits; phase control rectifiers; bridge converters - fully controlled and half controlled; principles of choppers and inverters; basis concepts of adjustable speed dc and ac drives.

Electrical and Electronic Measurements: Bridges and potentiometers; PMMC, moving iron, dynamometer and induction type instruments; measurement of voltage, current, power, energy and power factor; instrument transformers; digital voltmeters and multimeters; phase, time and frequency measurement; Q-meters; oscilloscopes; potentiometric recorders; error analysis.

Microprocessors and Microcontrollers: Architecture and Instruction set of 8086 Micro processor and 8051 Micro controller.